

Jing Shuang (Lisa) Li

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Academic Positions

Assistant Professor of Electrical Engineering and Computer Science Sep 2023 – Present
Michigan Neuroscience Institute Affiliate
University of Michigan, Ann Arbor MI

Education

Ph.D. in Control & Dynamical Systems Sep 2018 – Jun 2023
Thesis: Distributed Control Theory for Cyberphysical and Biological Systems
California Institute of Technology, Pasadena CA

B.A.Sc. in Engineering Science, Electrical and Computer Engineering Major Sep 2013 – Jun 2018
University of Toronto, Toronto ON

Publications

* denotes equal contribution

- [19] J. Ting, **J. S. Li**, “The Path Integral Bottleneck: Exploring the Control-Compute Tradeoff”, *in submission* [[pdf](#)]
- [18] J. Ting, **J. S. Li**, “Two-Layer Attention Optimization for Bimanual Coordination”, *2025 IEEE American Control Conference (ACC)*, pp. 2748–2754, 2025
- [17] **J. S. Li**, “Toward Neuronal Implementations of Delayed Optimal Control”, *2025 IEEE American Control Conference (ACC)*, pp. 2715–2721, 2025
- [16] Y. Du, **J. S. Li**, “State Feedback System Level Synthesis in Continuous Time”, *in submission* [[pdf](#)]
- [15] J. Zhao, M. Yang, **J. S. Li**, “Human Balancing on a Log: A Switched Multi-Layer Controller”, *2025 IEEE American Control Conference (ACC)*, pp. 1926–1931, 2025
- [14] L. Karashchuk*, **J. S. Li***, G. M. Chou, S. Walling-Bell, S. L. Brunton, J. C. Tuthill, B. W. Brunton, “Sensorimotor delays constrain robust locomotion in a 3D kinematic model of fly walking”, *eLife* 13:RP99005, 2024
- [13] A. Aspeel, J. Nylof, **J. S. Li**, N. Ozay, “A Low Rank Approach to Minimize Sensor-to-Actuator Communication in Finite Horizon Output Feedback”, *IEEE Control Systems Letters (L-CSS)*, pp. 3609–3614, 2023
- [12] **J. S. Li**, C. Amo Alonso, “Global Performance Guarantees for Localized Model Predictive Control”, *IEEE Open Journal of Control Systems*, vol. 2, pp. 325–336, 2023
- [11] **J. S. Li***, A. A. Sarma*, T. J. Sejnowski, J. C. Doyle, “Internal feedback in the cortical perception–action loop enables fast and accurate behavior”, *Proceedings of the National Academy of Sciences (PNAS)*, vol. 120 (39), pp. e2300445120, 2023

- [10] C. Amo Alonso, **J. S. Li**, N. Matni, J. Anderson, “Distributed and Localized Model Predictive Control—Part II: Theoretical Guarantees”, *IEEE Transactions on Control of Network Systems (TCNS)*, vol. 10 (3), pp. 1113–1123, 2023. **IEEE Transactions on Control of Network Systems Best Paper Award**
- [9] F. Xiao, **J. S. Li**, J. C. Doyle, “Flux Exponent Control Enables Prediction of Metabolism Dynamics”, *IEEE American Control Conference (ACC)*, pp. 1189–1194, 2023
- [8] **J. S. Li**, J. C. Doyle, “Distributed Robust Control for Systems with Structured Uncertainties”, *IEEE Conference on Decision and Control (CDC)*, pp. 1702–1707, 2022
- [7] L. Conger, **J. S. Li**, E. Mazumdar, S. L. Brunton, “Nonlinear System Level Synthesis for Polynomial Dynamical Systems”, *IEEE Conference on Decision and Control (CDC)*, pp. 3846–3852, 2022
- [6] C. Amo Alonso, **J. S. Li**, J. Anderson, N. Matni, “Distributed and Localized Model Predictive Control—Part I: Synthesis and Implementation”, *IEEE Transactions on Control of Network Systems (TCNS)*, vol. 10 (2), pp. 1058–1068, 2023
- [5] **J. S. Li**, “Internal Feedback in Biological Control: Locality and System Level Synthesis”, *IEEE American Control Conference (ACC)*, pp. 474–479, 2022. **Best Student Paper Finalist**
- [4] J. Stenberg, **J. S. Li**, A. A. Sarma, J. C. Doyle, “Internal Feedback in Biological Control: Diversity, Delays, and Standard Theory”, *IEEE American Control Conference (ACC)*, pp. 462–467, 2022
- [3] A. A. Sarma, **J. S. Li**, J. Stenberg, G. Card, E. S. Heckscher, N. Kasthuri, T. J. Sejnowski, J. C. Doyle, “Internal Feedback in Biological Control: Architectures and Examples”, *IEEE American Control Conference (ACC)*, pp. 456–461, 2022
- [2] **J. S. Li**, C. Amo Alonso, J. C. Doyle, “Frontiers in Scalable Distributed Control: SLS, MPC, and Beyond”, *IEEE American Control Conference (ACC)*, pp. 2720–2725, 2021
- [1] **J. S. Li**, D. Ho, “Separating Controller Design from Closed-Loop Design: A New Perspective on System-Level Controller Synthesis”, *IEEE American Control Conference (ACC)*, pp. 3529–3534, 2020

Toolboxes

- [T2] S. H. Tseng, **J. S. Li**, “SLSpy: Python-Based System-Level Controller Synthesis Framework”, 2020 [[pdf](#)] [[code](#)]
- [T1] **J. S. Li**, “SLS-MATLAB: MATLAB Toolbox for System Level Synthesis”, 2019. [[code](#)]

Invited Talks

- “Layered control in animal sensorimotor systems”. *Telluride Neuromorphic Cognition Engineering Workshop*, Jul 2025
- “Global Performance Guarantees for MPC Under Sparse Local Communication”. *Leveraging Sparsity in Control* workshop at *European Control Conference*, Jun 2025
- “What can control theory tell us about neural circuits?”. *Dynamics of brain computations through the lens of control theory* workshop at Computational and Systems Neuroscience (COSYNE) Conference, Apr 2024

“Layered control in animal sensorimotor systems”. *Control Architecture Theory* workshop at *IEEE Conference on Decision and Control*, Dec 2024

“Optimal control in sensorimotor systems”. *Autonomy Talks*, Jun 2024

“Optimal control in animal sensorimotor systems”. *10th Midwest Workshop on Control and Game Theory*, Apr 2024

“Optimal feedback control in sensorimotor systems: behavior and implementation”. *Manifolds in Nature Workshop*, Mar 2024

“Optimal and distributed control in animals”. University of Michigan, Jan 2024

“Control theory for neuroscience: from internal feedback to legged locomotion”. *Woods Hole Workshop on Computational Neuroscience/Telluride Neuromorphic Cognition Engineering Workshop*, Jul 2023

“Introduction to System Level Synthesis”. *System Level Synthesis: New Frontiers in Distributed Control* workshop at *IEEE Conference on Decision and Control*, Dec 2022

“Internal Feedback Pathways: From Control Theory to Sensorimotor Systems (and beyond)”. Center for Computational Neuroscience, Flatiron Institute, Nov 2021

Posters

J. C. Doyle, C. Amo Alonso, **J. S. Li**, F. Xiao, “Rule-Based Systems Theory for Regulation in Networks of Biomolecules, Microbial Cells and Populations”, *8th Build-a-Cell Workshop*, 2022

J. S. Li, “Internal Feedback: From Optimal Control to the Sensorimotor System”, *Chen Institute for Neuroscience Poster Session*, 2021

J. S. Li, S. H. Tseng, “SLS-MATLAB Toolbox: Do-It-Yourself System Level Synthesis”, *IEEE American Control Conference*, 2020

J. S. Li, J. Yu, C. Amo Alonso, J. C. Doyle, “System Level Synthesis: Distributed Control Made Easy”, Poster at *Center for Autonomous Systems and Technologies (CAST) Scientific Showcase*, Caltech, 2020

Teaching

Control Systems Analysis and Design (EECS 460)	F2024, F2025
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Special Topics: Control Theory for Biological Sensorimotor Systems (EECS 598)	W2024
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Linear Systems Theory (ECE 560)	F2023, W2025
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Advising & Mentorship

PhD	Master's	Undergraduate
Yaozhi Du, W2025 –	Enxu Liu, F2024	Aida Ruan, S/S2024
Jaidev Gill, F2024 –	Riley Bridges, S/S2024 – F2024	<i>WISE RP Summer Scholar</i>
Eric (Qin) He, F2024 –	Ethan Parham, S/S2024 – F2024	Anisha Sharma, S/S2024
Justin Ting, W2024 –	Prerana Lakshmanan, S/S2024	Mo Yang, S/S2024 – F2024
	Yaozhi Du, W2024 –	Jiayi Zhao, S/S2024 – F2024
	Qunzhuo Feng, F2023 – W2024	

W: Winter term (Jan – Apr); S/S: Spring/Summer term (May – Aug); F: Fall term (Sep – Dec)

Funding Awarded

NSERC PGSD (ranked 4/72 in electrical engineering)	Apr 2021
NSERC USRA (awarded twice)	May 2015, May 2016

Academic Service

Reviewer:

IEEE American Control Conference (ACC)	IEEE Trans. on Automatic Control (TAC)
IEEE Conference on Decision and Control (CDC)	IEEE Trans. on Control of Networked Systems (TCNS)
IEEE Control Systems Letters (L-CSS)	IEEE Trans. on Vehicular Technology
IEEE Open Journal of Control Systems (OJCSYS)	Neural Computation

Panel reviewer: Directorate for Engineering (ENG), NSF

Session chair/co-chair: ACC2025 Switched Systems; ACC2025 Biological and Bioinspired Systems

Poster/demo chair, 2024 ACM/IEEE International Conference on Cyber-Physical Systems

Lead workshop organizer, “System Level Synthesis: New Frontiers in Distributed Control” at IEEE Conference on Decision and Control (2022)

Additional Experience

Piano and Voice Instructor, Lippert Music Center	Sep 2012 – Jun 2018
Taught private music lessons and prepared students for Royal Conservatory exams and competitions	
Undergraduate Thesis, Reconfigurable Antenna Lab (advisor: S. Hum)	Sep 2017 – Apr 2018
Project: Neural network inverse models for electromagnetic metasurface design	
Full-Time Software Engineering Intern, Verity Studios AG	Sep 2016 – Aug 2017
Wrote code in Python, C++, and SQL to support drone flight planning, evaluation, and simulation	
Student Researcher, Reconfigurable Antenna Lab (advisor: S. Hum)	May 2016 – Aug 2016
Project: C++ simulation tool for periodic electromagnetic scatterers	
Student Researcher, Lab for Advanced Power Conversion (advisor: P. Lehn)	May 2015 – Aug 2015
Project: Wireless energy harvester for smart-grid monitoring applications	
Student Researcher, Nanomaterials Lab (advisor: H. G. Wei)	May 2014 – Aug 2014

Project: Copper-based nanostructures for photocatalytic hydrogen production

Additional Skills

Programming and scripting: MATLAB, Python, C++, SQL

Foreign languages: Mandarin Chinese (fluent), French (basic)

Instruments: piano, voice (classical, musical theatre, pop), cello, guitar

Certifications from the Royal Conservatory of Music:

Associate (ARCT) in Piano Performance, 1st Class Honours (practical only)

Grade 10 comprehensive certificate in Piano Performance, 1st Class Honours

Grade 10 comprehensive certificate in Vocal Performance, 1st Class Honours